

Notice of References Cited	Application/Control No. 10/538,770		Applicant(s)/Patent Under Reexamination OKAZAKI ET AL.	
	Examiner MCDIEUNEL MARC		Art Unit 3664	Page 1 of 1

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*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
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*	B	US-7,053,579	05-2006	Moridaira, Tomohisa	318/568.12
*	C	US-6,917,176	07-2005	Schempf et al.	318/568.11
*	D	US-3,851,769	12-1974	Noguchi et al.	414/744.3
*	E	US-4,166,543	09-1979	Dahlstrom, Lars	700/251
*	F	US-4,791,588	12-1988	Onda et al.	700/260
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NON-PATENT DOCUMENTS

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	U	Tan et al., Hybrid system design for singularityless task level robot controllers, 2000, IEEE, pg. 3007-3012			
	V	Gerke et al., Fuzzy collision avoidance for industrial robots, 1995, IEEE, pg. 510-517			
	W	Akella et al., Discontinuous model-based adaptive control for robots executing free and constrained tasks, 1994, IEEE, pg. 3000-3007			
	X	Hirana et al., Realization of skill controllers for manipulation of deformable objects based on hybrid automata, 2001, IEEE, pg. 2674-2679			

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.